# Control Plane Innovations to Realize Dynamic Formulation of Multicast Sessions in Inter-DC Software-Defined Elastic Optical Networks

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# Abstract

It is known that to support the applications such as datacenter backup and migration, multicast should be supported efficiently in inter-datacenter (inter-DC) networks to carry the corresponding point-to-multiple-point communications. Moreover, due to the traffic dynamics in inter-DC networks, we might have to consider the case that the multicast members can join or leave a multicast session dynamically. Therefore, in this work, we try to leverage control plane innovations to realize dynamic formulation of multicast sessions in inter-DC software-defined elastic optical networks (SD-EONs), which are equipped with multicast-incapable bandwidth-variable wavelength selective switches (MI-BV-WSS'). Here, one key issue to address is that the continuous changing of multicast group members can degrade the optimality of a multicast-tree. Hence, we propose to rearrange the multicast-trees adaptively to reduce their spectrum usage. Meanwhile, we try to minimize the frequency of rearrangements to avoid unnecessary operation complexity. Based on these considerations, we propose several multicast-tree rearrangement algorithms for updating multicast sessions dynamically with lightpath reroutings in inter-DC SD-EONs. Both partial and full multicast-tree rearrangements are studied. Simulation results indicate that the proposed algorithms can rearrange the multicast-trees intelligently such

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that the blocking probability can be reduced effectively with the least lightpath reroutings. Next, based on these theoretical investigations, we consider how to implement the proposed algorithms in the control plane of an inter-DC SD-EON. We extend the OpenFlow (OF) protocol to support the dynamic formulation of multicast sessions and also design the functional models in the control plane elements to realize multicast-tree rearrangements. Experiment results verify the effectiveness of our proposed algorithms and system design.

*Keywords:* Multicast, elastic optical networks (EONs), software-defined networking (SDN), inter-datacenter network (Inter-DC Network)

#### 1 1. Introduction

Recently, with the rise of inter-datacenter (inter-DC) networks, there have 2 been increasing demands for bandwidth-intensive applications such as datacen-3 ter backup and migration, cloud computing, and video streaming. For instance, Λ according to the latest statistics in Cisco's report [1], by 2019, the global Internet 5 traffic will surpass 2.0 ZettaBytes, 65% of which would come from video-related 6 applications. It is known that most of these applications are now leveraging the multi-DC cloud systems to achieve cost-effective and elastic services, and 8 need to transfer large amounts of data among geographically distributed end-9 systems [2]. Therefore, to support these services in inter-DC networks, multicast 10 should be supported efficiently to carry the corresponding point-to-multiple-11 point communications [3, 4]. Meanwhile, with the tremendous bandwidth in 12 optical fibers, optical networks provide a viable infrastructure for delivering 13 high-throughput traffics. More importantly, the newly-developed elastic optical 14 networks (EONs) can make the resource management in the optical layer more 15 adaptive and application-aware than the traditional fixed-grid wavelength divi-16 sion multiplexing (WDM) networks [5, 6]. Specifically, with bandwidth-variable 17 transponders (BV-Ts) and switches (BV-WSS'), EONs provision bandwidth by 18 grooming the capacities of several narrow-band frequency slots (FS'). Hence, 19 EONs can achieve agile spectrum management and provision requests with var-20

ious bandwidth requirements more efficiently. These advantages match with the 21 requirements of inter-DC networks well, and thus EON has been considered as 22 a promising physical infrastructure to carry future inter-DC networks [2, 7, 8]. 23 The problem of multicast in EONs was first studied in [9], where the authors 24 proposed two heuristics to solve the routing and spectrum assignment (RSA) 25 for all-optical multicast. Later on, we formulated integer linear programming 26 (ILP) models and developed heuristics with better performance in [10, 11]. The 27 problem of provisioning multiple static multicast sessions in WDM network was 28 studied in [12]. In this work, we also try to accommodate multiple multicast 29 sessions in an EON but in a dynamic manner. In [13], we considered the sce-30 nario where one multicast session can be provisioned with multiple sub-trees 31 to adapt to the physical-layer impairments. However, since this work focus-32 es on the dynamic formulation of multicast sessions in EONs, we still assume 33 that each multicast session only uses one multicast-tree. Note that, with minor 34 modifications, the scheme proposed in this work can be extended to support 35 the scenario discussed in [13]. Walkowiak et al. [14] considered a joint opti-36 mization of multicast and unicast flows in EONs, with the focus only on offline 37 optimization. Nevertheless, the studies mentioned above assumed that all the 38 BV-WSS' in EONs are multicast-capable (MC) (*i.e.*, supporting light-splitting). 39 Note that, MC optical switches usually have complicated structures [15] and can 40 be prohibitively expensive. Therefore, it would not be economical to build an 41 optical network solely with them. To address this issue, people have investigat-42 ed how to realize multicast in optical networks built with multicast-incapable 43 (MI) switches [16, 17]. Specifically, they leveraged multiple unicast lightpaths 44 to set up the logic light-tree for a multicast request (*i.e.*, overlay multicast). 45

<sup>46</sup> Note that, previous studies on multicast in EONs only considered the static <sup>47</sup> formulation of multicast sessions, *i.e.*, the multicast group members stay un-<sup>48</sup> changed for the whole life-time of a multicast session. However, in order to sup-<sup>49</sup> port the emerging applications such as grid computing, dynamic data backup <sup>50</sup> /synchronization and high-definition teleconferencing, we might have to consid-<sup>51</sup> er the case that the multicast members can join or leave a multicast session dynamically. To the best of our knowledge, dynamic formulation of multicast
sessions in EONs has not been studied so far.

In order to achieve dynamic formulation of multicast sessions efficiently in 54 inter-DC EONs, we need to know the global resource utilization and the infor-55 mation of all the in-service requests in the network. This brings new challenges 56 to the network control and management (NC&M). Fortunately, it is known that 57 software-defined networking (SDN) with OpenFlow (OF) [18] can improve op-58 tical networks' programmability by decoupling their control and data planes 59 and leveraging centralized NC&M [19, 20, 21]. The combination of SDN and 60 EON leads to software-defined EONs (SD-EONs) and can further improve the 61 flexibility of EONs [19, 20, 21, 22, 23, 24]. Note that, SD-EONs can be real-62 ized by leveraging OpenFlow switches (e.q., Pica 8 [25]) together with flexible-63 grid reconfigurable add/drop multiplexers (ROADMs) [26]. More promising-64 ly, leading vendors of optical network equipment such as Alcatel-Lucent have 65 already utilized the concept of SD-EON to offer agile optical networking so-66 lutions, which make SDN architecture work with flexible-grid ROADMs [27]. 67 Therefore, SD-EONs provide new opportunities on provisioning the services ef-68 ficiently for dynamic multicast sessions. In line with this, we can leverage the 69 centralized NC&M in SD-EONs to utilize the network resources (e.g., optical70 spectra, optical-to-electrical-to-optical (O/E/O) converters, etc) cost-effectively. 71 For instance, under the assumptions that all the BV-WSS' in SD-EONs are MC 72 and multicast sessions are formulated statically, the authors of [4] have already 73 studied the control plane operations for setting up multicast sessions, and we 74 have also demonstrated the fragmentation-aware service provisioning for ad-75 vance reservation multicast [28]. 76

In this paper, we try to leverage control plane innovations to realize dynamic formulation of multicast sessions in inter-DC SD-EONs that are equipped with MI BV-WSS'. Here, one key issue to consider is that the continuous changing of multicast group members causes the degradation of the multicast-tree. Therefore, we propose to rearrange the multicast-trees adaptively to reduce their spectrum usages. Meanwhile, we try to minimize the frequency of rearrangements

to avoid unnecessary operation complexity. Based on these considerations, we 83 propose several multicast-tree rearrangement algorithms for updating multicas-84 t sessions dynamically with lightpath reroutings in inter-DC SD-EONs. Both 85 partial and full multicast-tree rearrangements are addressed. Simulation results 86 indicate that the proposed algorithms can rearrange the multicast-trees intel-87 ligently such that the blocking probability can be reduced effectively with the 88 least lightpath reroutings. Next, based on these theoretical investigations, we 89 consider how to implement the proposed algorithms in the control plane of an 90 inter-DC SD-EON. We extend the OF protocol to support the dynamic formu-91 lation of multicast sessions and also design the functional models in the control 92 plane elements to realize multicast-tree rearrangements. Experiment results 93 verify the effectiveness of our proposed algorithms and system design. 94

The rest of the paper is organized as follows. We formulate the problem of dynamic formulation of multicast sessions in inter-DC EONs in Section 2. Section 3 discusses the proposed multicast-tree rearrangement algorithms. The numerical simulation results are presented in Section 4 for performance evaluation. We describe the system design for realizing dynamic formulation of multicast sessions in an inter-DC SD-EON in Section 5 and show the experimental results in Section 6. Finally, Section 7 summarizes the paper.

## 102 2. Problem Formulation

#### 103 2.1. Network Model

We model the topology of the inter-DC EON as G(V, E), where V is the set of DCs and E is the fiber link set. Since we consider an MI-EON, all the DCs in V are equipped with MI switches, *i.e.*, none of them is capable of performing light-splitting. There are F FS' on each link in E. Note that, we assume that the SD-EON is equipped with the sliceable BV-Ts discussed in [29]. Specifically, as long as there are enough spectrum resources on a fiber, the BV-Ts connecting to it can always be sliced and tuned to support the requested optical transmission. Hence, this model merges the constraints on spectra and BV-Ts into one, and we do not need to consider the BV-T constraint explicitly. Each FS has a bandwidth of 12.5 GHz and can provide a capacity of  $C_{FS} = 12.5$  Gb/s if its modulation format is BPSK [5]. In this work, we consider distance-adaptive modulation selection [10], and assume that there are four feasible modulation formats, *i.e.*, BPSK, QPSK, 8QAM and 16QAM, in the EON. Here, we consider the scenario where there is a set of multicast sessions to be served. For each multicast session MR(s, D, C), where s is the source node and D is the set of destinations, we use the OL-M-SFMOR scheme in [16] to determine the routing, modulation and spectrum assignment (RMSA) for it and try to satisfy the capacity requirement C of each destination in D. Note that as we consider dynamic multicast sessions, D can change over time and the RMSA needs to be adjusted accordingly. Here, we define the modulation-level as m = 1, 2, 3 and 4 for BPSK, QPSK, 8QAM and 16QAM, respectively. Hence, the number of spectrally-contiguous FS' that need to be assigned for MR is [10]

$$n = \left\lceil \frac{C}{m \cdot C_{FS}} \right\rceil + N_{gb},\tag{1}$$

where  $N_{gb}$  is the guard-band FS'. Note that similar to our work in [16], we still assume that the spectrum assignment and modulation selection of a multicastbranch can be changed by a relay node on the multicast-tree. Meanwhile, the maximum transmission reaches of BPSK, QPSK, 8QAM and 16QAM signals are set as 5000 km, 2500 km, 1250 km and 625 km, respectively, with the same assumptions as those in [10].

#### 110 2.2. Design Considerations

With a multicast session MR(s, D, C), we define its member nodes as the source s and all the destinations in D. In order to cover all the member nodes, we need to formulate a logic tree  $\mathcal{T}$  and set up a set of unicast lightpaths  $\mathcal{P}$ to support it. According to OL-M-SFMOR, each lightpath  $p \in \mathcal{P}$  can only start and end at the member nodes of MR. Hence, redundant BV-Ts can be avoided. Note that the signal is transmitted all-optically end-to-end on each lightpath  $p \in \mathcal{P}$  and the RMSAs of different lightpaths are independent.



Figure 1: Example on the multicast-tree of a dynamic multicast session losing the optimal structure over time, (a) original multicast-tree, (b) the optimal multicast-tree for the new multicast group.

<sup>118</sup> When determining the RMSA of a lightpath  $p \in \mathcal{P}$ , we use distance-adaptive <sup>119</sup> modulation selection and follow the spectrum contiguous, non-overlapping and <sup>120</sup> continuity constraints.

As D can change on-the-fly, we have to address the issue that its multicast-121 tree loses the optimal structure due to the operation principle of OL-M-SFMOR. 122 For instance, Fig. 1 shows an illustrative example. We first have a session with 123 s = 1 and  $D = \{3, 4, 5\}$ , and the session is set up as shown in Fig. 1(a). DC 124 3 sends the traffic flow to the local port and also forwards it to DCs 4 and 5 125 through all-optical paths, respectively. Then, DC 6 tries to join the multicast 126 session, while the multicast service to DC 3 is expiring. Without the tree rear-127 rangement, we cannot remove DC 3 from the multicast-tree because it still has 128 downstream nodes. Consequently, the spectrum assignment of the multicast-129 tree represented by the dashed lines in Fig. 1(b) is sub-optimal and certain 130 spectra are wasted. On the other hand, we can rearrange the multicast-tree to 131 the one with the solid lines in Fig. 1(b), and apparently, after we updating the 132 dynamic multicast sessions adaptively, the efficiency of the spectrum usage gets 133 improved significantly. 134

#### 1 while MI-EON is operational do if multicast session MR(s, D, C) first appears then 2 use OL-M-SFMOR to build a logic tree $\mathcal{T}$ that covers $\{s, D\}$ ; 3 set up the lightpaths $\mathcal{P}$ to support $\mathcal{T}$ ; 4 else $\mathbf{5}$ if a new member v to join MR then 6 for each existing member $u \in \{s, D\}$ do $\mathbf{7}$ calculate K shortest paths for $u \to v$ ; 8 get RMSA for each path with FMA; 9 end 10 select path that has the least fragmentation cost to connect 11 v to session MR; update $\mathcal{T}$ to include the new branch; $\mathbf{12}$ end 13 if a member v to leave MR then $\mathbf{14}$ if v has downstream member(s) then 15mark v as a non-member in $\mathcal{T}$ ; 16 else $\mathbf{17}$ remove v and the branch to its upstream member from $\mathcal{T}$ ; 18 end 19 end $\mathbf{20}$ if a service provisioning period is about to end then $\mathbf{21}$ select multicast-trees for rearrangements; $\mathbf{22}$ rearrange the selected multicast-trees; 23 end 24 end $\mathbf{25}$ 26 end

# Algorithm 1: Dynamic Formulation of Multicast Sessions in MI-EONs

## 135 3. Dynamic Formulation of Multicast Sessions

#### 136 3.1. Overall Procedure

Algorithm 1 shows the overall procedure for dynamic formulation of mul-137 ticast sessions in MI-EONs. As shown in Lines 2-4, when a multicast session 138 MR(s, D, C) first appears, we leverage OL-M-SFMOR to set up the unicas-139 t lightpaths  $\mathcal{P}$  that formulate a logic tree  $\mathcal{T}$  to cover all the member nodes. 140 Meanwhile, the RMSA of each lightpath  $p \in \mathcal{P}$  is also determined. Lines 6-13 141 explain the operations for adding a new member in session MR. Specifically, 142 when a new member v tries to join the session, we leverage the reverse-anycast 143 scheme to establish the transmission for it, *i.e.*, we can use any existing mem-144 ber in  $\{s, D\}$  to relay the multicast transmission to v with a new lightpath. For 145 each existing member in  $\{s, D\}$ , we calculate K shortest paths to v and deter-146 mine the corresponding RMSAs with the fragmentation and misalignment-aware 147 spectrum assignment (FMA) in [30]. Then, we select the path that has the least 148 fragmentation cost to connect v to session MR. 149

Then, if a member  $v \in D$  needs to leave MR, Line 15 checks whether v 150 has any downstream member(s). If yes, Line 16 marks v as a non-member 151 relay node (NM-RN) in  $\mathcal{T}$ . Otherwise, *Line* 18 removes v and the branch to 152 its upstream member from  $\mathcal{T}$  and releases the associated spectrum resources. 153 For the multicast-tree rearrangement, we need to balance the tradeoff between 154 structure optimality and rearrangement frequency. Lines 21-24 show the related 155 operations. Basically, the MI-EON performs the multicast-tree rearrangement 156 when each service provisioning period is about to end. We first choose the 157 multicast sessions to rearrange with a tree selection strategy and then rearrange 158 the selected sessions. We propose two tree selection strategies and consider both 159 full and partial rearrangements of selected multicast-trees. 160

# <sup>161</sup> 3.2. Tree Selection Strategies

<sup>162</sup> When the EON is operational, there will be multiple active multicast sessions <sup>163</sup> in it. In order to reduce operation complexity, we develop two kinds of tree  $_{164}$  selection strategies that can intelligently select the most "critical" sessions (*i.e.*,

<sup>165</sup> the multicast sessions that are off the optimal RMSAs the most) to rearrange.

#### <sup>166</sup> 3.2.1. $\mathcal{D}$ -value based Tree Selection (DTS)

**Definition 1.** We define the  $\mathcal{D}$ -value of a multicast-tree  $\mathcal{T}$  as the hop-count of its longest source-destination branch, i.e., the multicast-tree's depth. Specifically, we have

$$\mathcal{D}(\mathcal{T}) = \max(hops(s \to d), \ \forall d \in D), \tag{2}$$

<sup>167</sup> where  $hops(\cdot)$  returns the hop-count of a path.

With the example in Fig. 1, we find that for a multicast session MR(s, D, C), 168 if the  $\mathcal{D}$ -value of its multicast-tree  $\mathcal{T}$  is abnormally large, the possibility that 169  $\mathcal{T}$  is sub-optimal is relatively high. Then, when we need to select multicast 170 sessions to rearrange, we calculate  $\mathcal{D}$ -values of all the multicast-trees and get 171 the average value  $\overline{\mathcal{D}}$ . If the  $\mathcal{D}$ -value of a multicast-tree is larger than  $\overline{\mathcal{D}}$ , the 172  $\mathcal{D}$ -value based tree selection strategy (DTS) chooses to rearrange it. Note that, 173 the  $\mathcal{D}$ -value of a multicast-tree can have a large absolute value for a few reason-174 s, e.g., the network has a relatively large topology and/or the locations of the 175 source and destinations are dispersed in the network. This is actually the reason 176 why we do not design DTS to use an arbitrary and fixed threshold on  $\mathcal{D}$ -values. 177 Nevertheless, by comparing  $\mathcal{D}$ -values with their average value  $\overline{\mathcal{D}}$ , the effects of 178 these topology-related disturbances can be minimized. Then, with this design, 179 we can select the real sub-optimal multicast-trees, e.g., those contain many NM-180 RNs, such as DC 3 in Fig. 1(b), and/or those use non-optimal relay nodes on 181 some of their branches. The time complexity of DTS to choose the most "crit-182 ical" multicast-trees is  $O(|\mathcal{T}|)$ , where  $|\mathcal{T}|$  is the number of in-service multicast 183 sessions in the network. 184

## 185 3.2.2. Q-value based Tree Selection (QTS)

DTS only considers the longest branch of a multicast-tree, but does not address its overall structure or the spectrum assignments on the links. Hence, we introduce the definition below. **Definition 2.** We define the Q-value of a multicast-tree T for a multicast session MR(s, D, C) as

$$Q(\mathcal{T}) = \frac{hops(\mathcal{T}^*) \cdot hidx(\mathcal{T}^*)}{hops(\mathcal{T}) \cdot hidx(\mathcal{T})},$$
(3)

where  $\mathcal{T}^*$  is the approximate optimal multicast-tree to carry the multicast session based on the current network status, hops(·) returns the total hop-count of a multicast-tree, and hidx(·) supplies the highest index of the used FS' of a multicast-tree. Here,  $\mathcal{T}^*$  can be obtained by using a clean-slate approach, i.e., calculating the multicast-tree with OL-M-SFMOR in [16] to cover  $\{s, D\}$  as MR(s, D, C) just comes in as a new session.

Obviously, if the RMSA of a multicast-tree  $\mathcal{T}$  approaches to that of  $\mathcal{T}^*$ , its  $\mathcal{Q}$ -value increases. Hence, the  $\mathcal{Q}$ -value based tree selection (QTS) takes a preset lower-bound on  $\mathcal{Q}$ -value as  $\mathcal{Q}_{lb}$ , and will select a multicast-tree for rearrangement if its  $\mathcal{Q}$ -value is smaller than  $\mathcal{Q}_{lb}$ . The complexity for calculate  $\mathcal{T}^*$  using OL-M-SFMOR in [16] is  $O(|V|^3)$ , where |V| is the number of the nodes in the topology. Then, the time complexity of QTS to choose the most "critical" multicast-trees is  $O(|\mathcal{T}| \cdot |V|^3)$ .

#### <sup>202</sup> 3.3. Tree Rearrangement with Lightpath Rerouting

For tree rearrangements, we have to minimize traffic disruptions and this can be done by leveraging the "make-before-break" scenario [30], *i.e.*, install new paths before tearing down old paths. Here, we consider two scenarios, *i.e.*, full and partial rearrangements of selected multicast-trees.

207 3.3.1. Full Rearrangement

Full rearrangement is straightforward. Basically, when a multicast session is selected, we recalculate the approximate optimal multicast-tree with OL-M-SFMOR and re-establish the session with it in the clean-slate manner.

# 211 3.3.2. Partial Rearrangement

Partial rearrangement tries to further balance the tradeoff between structure optimality and operation complexity by only modifying certain parts of



Figure 2: Example for the node-compression approach, (a) finding expiring-regions in  $\mathcal{T}$ , and (b) removing expiring-regions and reconnecting downstream members.

a multicast-tree. As shown in *Line* 16 of *Algorithm* 1, when a member node 214 has left the multicast session, it cannot be removed immediately if it still has 215 downstream member(s). Instead, we just mark it as an NM-RN. These NM-216 RNs cost redundant spectrum usages on links and consume unnecessary O/E/O 217 converters, and thus should be minimized in the tree rearrangements. In order 218 to achieve this, we introduce a node-compression approach. Specifically, with 219 a multicast-tree  $\mathcal{T}$ , we first abstract all the transparent lightpaths on it as di-220 rected virtual links and obtain a virtual tree  $\mathcal{T}'$ . Then, if multiple NM-RNs 221 are adjacent on  $\mathcal{T}'$ , we compress them as an expiring-region. Fig. 2 shows 222 an illustrative example of the node-compression. The partial rearrangements 223 first reconnects all the downstream members of expiring regions in  $\mathcal{T}$ , and then 224 removes the expiring regions. 225

After handling the expiring-regions, we try to address the sub-optimal lightpaths in  $\mathcal{T}$ . Specifically, for a destination  $d \in D$ , we define its cost as

$$Cost(d) = hops(s \to d) \cdot hidx(v \to d), \tag{4}$$

where  $s \to d$  refers to the lightpath from s to d,  $hops(\cdot)$  returns the hop-count of a lightpath, v is the upstream relay node of d,  $v \to d$  is the transparent lightpath from v to d, and  $hidx(\cdot)$  supplies the highest index of the used FS' of a transparent lightpath. The cost jointly considers the hop-count of the sourcedestination branch of d and the spectrum assignment for d. Then, we define the



Figure 3: Lightpath rerouting for costly destinations, (a) finding costly destinations and reconnecting the destinations, and (b) new multicast-tree.

cost threshold as

$$Cost_{th} = \frac{hidx(\mathcal{T})}{|D|} \cdot \sum_{u \in D} hops(s \to u), \tag{5}$$

where |D| represents the number of destinations.  $Cost_{th}$  presents the average cost of destinations in  $\mathcal{T}$ , where  $\frac{\sum hops(s \to u)}{|D|}$  represents the average hop-count from source to destinations. If the cost of a destination is higher than  $Cost_{th}$ , we will reroute its transparent lightpath with the procedure in *Algorithm* 2. Specifically, we still use the reverse-anycast scheme as shown in *Lines* 6-12. Fig. 3 gives an example on the lightpath rerouting for costly destinations. Finally, *Algorithm* 3 shows the overall procedure of partial rearrangement for a multicast session MR(s, D, C).

## 234 4. Numerical Simulations

In this section, we use simulations to evaluate the proposed algorithms for dynamic formulation of multicast sessions in inter-DC EONs. We consider two physical topologies, *i.e.*, the 14-node NSFNET topology and the 28-node US Backbone topology [10]. The EON is deployed in the C-band and hence, each fiber link can accommodate F = 358 FS' (*i.e.*, each FS' bandwidth is 12.5 GHz),

Algorithm 2: Lightpath Rerouting for Costly Destinations							
1 Ca	1 calculate $Cost_{th}$ with Eq. (5);						
2 fo	<b>r</b> each destination $d \in D$ <b>do</b>						
3	calculate $Cost(d)$ with Eq. (4);						
4	if $Cost(d) > Cost_{th}$ then						
5	obtain the upstream relay node $v$ of $d$ ;						
6	for each existing member $u \in \{s, D\} \setminus \{d\}$ do						
7	calculate K shortest paths for $u \to d$ ;						
8	get RMSA for each path with FMA;						
9	end						
10	select path that has the least fragmentation cost to reconnect $\boldsymbol{d}$						
	to session $MR$ ;						
11	tear down transparent lightpath $v \to d$ ;						
12	update $\mathcal{T}$ to include the new branch;						
13	13 end						
14 ei	14 end						

Algorithm 3: Partial Multicast-Tree Rearrangement

- 1 perform node-compression to find the expiring-regions;
- 2 reconnect downstream members of expiring-regions in  $\mathcal{T}$ ;
- **3** remove the expiring-regions;
- ${\tt 4}$  apply Algorithm 2 to reroute light paths for costly destinations;

which correspond to 4.475 THz bandwidth [10]. The multicast requests are 240 generated using the Poisson traffic model, *i.e.*, requests come in according to the 241 Poisson process with an average arrival rate of  $\lambda$  and their holding time follows a 242 negative exponential distribution with an average of  $\frac{1}{\mu}$ . Hence, we can quantify 243 the traffic load with  $\frac{\lambda}{\mu}$  in Erlangs. Each request carries the information on source 244 and destination node(s), the multicast session to join, and required capacity 245 in Gb/s. The capacity requirements of the multicast sessions are uniformly 246 distributed within [50, 400] Gb/s. 247

We first compare the performance of the algorithms for dynamic formulation 248 of multicast sessions with different tree rearrangement schemes. Fig. 4 shows 249 the results on blocking probability. In the plots, the curves for "N/R" imply the 250 scheme that we do not apply tree rearrangement, *i.e.*, *Lines* 21-24 in *Algorithm* 251 1 are not executed. For the algorithms that use DTS as the tree selection strat-252 egy, we consider both full rearrangement (DTS-F) and partial rearrangement 253 (DTS-P). Note that here the "full" rearrangement refers to the operation on a 254 selected multicast-tree but not all the multicast-trees in the network, *i.e.*, when 255 a multicast-tree is selected, we recalculate the approximate optimal tree struc-256 ture and re-establish the session with it. Similarly, QTS-F and QTS-P denote 257 the algorithms that use QTS with full and partial rearrangements, respectively. 258 Specifically, for QTS-F, we have  $Q_{lb} = 0.7$ , *i.e.*, a multicast-tree will be selected 259 for rearrangement if its Q-value is less than 0.7, and QTS-P also uses  $Q_{lb} = 0.7$ . 260 As expected, tree rearrangement can effectively improve the blocking perfor-261 mance, as the algorithms with it provide lower blocking probabilities than the 262 N/R scheme in both topologies. In general, compared with partial rearrange-263 ment, full rearrangement can improve the blocking performance further. We also 264 observe that when the rearrangement scheme is the same, the QTS-based algorithm outperforms the DTS-based one in terms of blocking probability. This is 266 because QTS considers both the overall tree structure and spectrum utilization 267 in the tree selection strategy. 268 Table 1 summarizes the results on the average lightpath reroutings per ser-269

<sup>270</sup> vice provisioning period for the dynamic formulation of multicast sessions. It



(b) US Backbone topology.

Figure 4: Results on blocking probability.

Traffic Load	NSFNET				US Backbone			
(Erlangs)	DTS-F	DTS-P	QTS-F	QTS-P	DTS-F	DTS-P	QTS-F	QTS-P
400	71	11	15	6	55	12	15	6
600	94	16	21	8	90	20	22	11
800	118	20	25	11	121	26	28	15
1000	131	24	30	13	143	31	32	18

Table 1: Average lightpath reroutings per service provisioning period

is exciting to notice that the QTS-based algorithm also invokes significantly 271 less number of lightpath reroutings than the DTS-based one, when the rear-272 rangement scheme is the same. This observation suggests that the QTS-based 273 algorithms can provide lower blocking probability with a smaller number of 274 lightpath reroutings (*i.e.*,  $\frac{1}{4} \sim \frac{1}{3}$  of those performed in DTS-based algorithms). 275 This verifies that QTS can intelligently select the most "critical" multicast-trees 276 to rearrange. When comparing the results from QTS-F and QTS-P, we can see 277 that QTS-P can further reduce the number of lightpath reroutings significant-278 ly. Basically, for the simulations in both topologies, QTS-P only uses  $37\% \sim$ 279 56% number of lightpath reroutings, when being compared with QTS-F. Note 280 that, we use the same  $Q_{lb}$  in QTS-P, which means that in the simulations, a 281 multicast-tree has the same probability to be selected for rearrangement. 282

We then run more simulations to investigate the performance of QTS-P fur-283 ther. Basically, we notice that for QTS-P, there is a tradeoff between the block-284 ing performance and operation complexity, which can be adjusted by varying 285  $\mathcal{Q}_{lb}$ . Here, we name the algorithms as QTS-P- $\mathcal{Q}_{lb}$ . For example, QTS-P-0.9 286 means that the QTS-P algorithm adopts  $Q_{lb} = 0.9$ . Note that if we have 287  $Q_{lb} = 0$ , then QTS-P becomes "N/R". Here, due to the page limit, we on-288 ly show the results from the simulations that use the US Backbone topology, 289 but we do confirm that the results from the NSFNET topology follow the sim-290 ilar trends. Fig. 5 illustrates the effect of  $\mathcal{Q}_{lb}$  on the blocking performance of 291



Figure 5: Results on blocking probability of QTS-P (US Backbone).

QTS-P. Apparently, a larger  $Q_{lb}$  generally leads to lower blocking probability 292 in the network. This can be explained as follows. When  $Q_{lb}$  is larger, the 293 restriction on the optimality of multicast-trees becomes stricter according to 294 Eq. (3). Consequently, QTS-P using high  $Q_{lb}$  considers more multicast-trees 295 as sub-optimal and selects them to rearrange. Therefore, QTS-P invokes more 296 lightpath reroutings and provides better blocking performance. However, the 297 operation complexity also increases when the network needs to accomplish more 298 lightpath reroutings. Moreover, it is interesting to notice that the blocking per-299 formance of QTS-P does not increase evenly with  $\mathcal{Q}_{lb}$ . Specifically, we observe 300 that the blocking probability only reduces slightly if we increase  $Q_{lb}$  over 0.5. 301 Therefore, we can draw the conclusion that when  $Q_{lb} > 0.5$ , the optimization 302 margin that QTS-P can obtain by increasing  $\mathcal{Q}_{lb}$  is very limited. 303

Table 2 summarizes the results on average lightpath reroutings per service provisioning period for QTS-P using different  $Q_{th}$ . As expected, a larger  $Q_{lb}$ leads to more lightpath reroutings. We can also see that the number of lightpath

Traffic Load			QTS-P		
(Erlangs)	$Q_{lb} = 0.1$	$Q_{lb} = 0.3$	$Q_{lb} = 0.5$	$Q_{lb} = 0.7$	$Q_{lb} = 0.9$
400	0.5	2.3	4.2	6.4	9.4
600	0.8	3.5	6.8	10.8	16.1
800	0.8	4.3	9.0	14.6	22.0
1000	0.9	4.9	10.7	18.0	27.7

Table 2: Average lightpath reroutings per service provisioning period (US Backbone)

<sup>307</sup> reroutings keeps increasing when  $Q_{lb} \ge 0.5$ . However, as Fig. 5 shows, the <sup>308</sup> blocking probability reduction becomes very limited when  $Q_{lb} \ge 0.5$ . Hence, <sup>309</sup> for the joint consideration of blocking probability and operation complexity, we <sup>310</sup> think that  $Q_{lb} = 0.5$  is the proper value to be used in QTS-P.

Fig. 6 shows the results on the average number of O/E/O converters per multicast destination. It can be seen that compared with N/R, QTS-P can achieve around 29% reduction on the O/E/O converter usage on average. We also observe that DTS-based strategies use less O/E/O converters than QTSbased ones, which is because DTS-based strategies focus on the long sourcedestination branches of multicast-trees which may contains NM-RNs.

# 317 5. Control Plane System Design

In this section, we describe the system design for realizing dynamic formulation of multicast sessions in an inter-DC SD-EON.

# 320 5.1. Network Architecture

Fig. 7 shows the architecture of inter-DC SD-EON. The network consists of two separated planes, *i.e.*, the data and control planes. The data plane consists of several geographically distributed DCs, each of which attaches to a multicast-incapable BV-WSS (MI-BV-WSS), which can be used to set up multicast sessions for inter-DC data transmissions. The control plane consists



Figure 6: Average number of O/E/O converters per multicast destination (US Backbone).

of several OpenFlow agents (OF-AGs) and an OpenFlow controller (OF-C) [19, 20]. Each OF-AG is attached to an MI-BV-WSS to manage the network element according to the instructions from OF-C.

# 329 5.2. System Functional Design

The functional modules inside the OF-AG and OF-C are shown in the Fig. 330 8. In OF-C, the network abstraction module (NAM) communicates with 331 the OF-AGs to abstract the data plane information (e.g., network topology)332 and sends the information to the traffic engineering database (TED). TED 333 stores the information on the spectrum utilization and lightpaths and assists the 334 resources computing and allocation module (RCAM) to provision new 335 multicast sessions or reconfigure existing ones. The tree rearrangement algorith-336 m runs in the multicast session reconfiguration module (MRM). MRM 337 gets the information of in-service sessions from the multicast session man-338 agement module (MMM). The provisioning and reconfiguration strategies 339



Figure 7: Network architecture of an inter-DC SD-EON.



Figure 8: Functional modules in OF-C and OF-AG to enable dynamic formulation of multicast sessions.

are defined by **network management system (NMS)** and configured with the **policy module (Policy)**. According to the outputs of **multicast session provisioning module (MPM)** or MRM, RCAM computes the resource allocations, and then it encodes the provisioning or reconfiguration schemes in OF-messages and sends them to related OF-AGs. The OF client in an OF-AG communicates with OF-C using a multicast-enabled extended OF protocol, and the flow entries that are used to configure the data plane network elements are stored in the local traffic database (LTD) [21].

#### 348 5.3. OF Extension for Dynamic Formulation of Multicast Sessions

According to the working principle of OF, the inter-DC SD-EON identifies 349 each lightpath as an optical flow with the flow-entry that consists of match-350 ing fields, actions and related counters [18]. We implement a control plane 351 system for the inter-DC SD-EON based on OF v1.0 [18] since it is a stable 352 version and widely supported by various OF systems. We propose an extension 353 of the matching fields to support dynamic formulation of multicast session-354 s. Specifically, to identify a multicast session, the matching fields are Mul-355 ticast\_Group\_Address, Starting\_Frequency and Number\_of\_Frequency 356 \_Slots. Note that, we use multicast group addresses to identify a set of destina-357 tions in the network topology, and the mapping between them is pre-determined. 358 By doing so, we do not need to encode a long list of destination addresses in 359 OF messages and achieve good scalability. Specifically, in G(V, E), we assign a 360 unique multicast group address to each combination of multiple nodes, and thus 361 we need to assign  $2^{|V|} - |V| - 1$  multicast group addresses in total. We also add a 362 "Re-Flag" field in the related OF messages to indicate whether a message is for 363 provisioning a new session or reconfiguring an existing one. Meanwhile, to let 364 an OF-AG know whether an OF message is for installing a new connection or 365 tearing down an existing one, we include a "Command" field. For the actions, 366 we create **SET\_MULTICAST\_GROUP\_ADDRESS** as a new action type, 367 which is used to set new multicast group address when a multicast session's 368 destinations have been changed. 360



Figure 9: Experimental setup with the NSFNET topology.

## 370 6. Experimental Demonstrations

We implement the aforementioned design in a control plane testbed for an 371 inter-DC SD-EON, which is built with high performance servers (ThinkServer 372 RD530). We have 14 OF-AGs that each runs on an independent server, and 373 they are connected according to the scheme in Fig. 9 to mimic the NSFNET 374 topology. Each OF-AG is programmed based on Open-vSwitch [31] running 375 on Linux. The OF-C is implemented with the POX platform [32] and runs 376 on another independent server that is directly connected to all the OF-AGs. 377 Similar to our previous work in [20, 21], we only focus on the control plane 378 implementation for the dynamic provisioning and reconfiguration of multicast 379 sessions, and the network elements in the data plane (e.g., MI-BV-WSS') are 380 software-emulated. 381

We first show the procedure for provisioning a new multicast session dynami-382 cally in the testbed. Fig. 10 shows the Packet\_In message for setting up the new 383 multicast session, which shows that the source is DC 9, the multicast group ad-384 dress is 7, *i.e.*, corresponding to the destination set DCs {7,10}. Fig. 11 shows 385 the Wireshark capture for the OF messages used to provision the multicast ses-386 sion. To establish the logic multicast-tree for the session, OF-C configures two 387 lightpaths, as  $9 \rightarrow 10$  and  $10 \rightarrow 7$ . Figs. 12-14 show the *Flow\_Mod* message 388 received by different nodes on the logic multicast-tree. Specifically, the OF-AG 380

```
⊽ Header
   version: 1
   Type: PacketIn (10)
   length: 108
   xid: 0
 Buffer_id: 688
 Total_len: 90
 In_port: 65534
 Reason: No_match (0)
⊽ Match
   Source: DC_9 (9)
   Type: Multicast (1)
   Tree_Id: 8
   Capacity_Requirement_GHz: 25
   Multicast_Group_Address: 7
   Expiring_Time: 2
```

Figure 10:  $Packet\_In$  message for setting up a multicast session.

					Multicast request arrives	]
	Time	Source	Destination	Protocol	Info	~
	3.491114	Node_9	Controller	OF-M-Ext	58132 > 1315 [Type:PacketIn]	
	3.503947	Controller	Node_7	OF-M-Ext	1315 > 35309 [Type:FlowMod]	
	3.504184	Controller	Node_10	OF-M-Ext	1315 > 41148 [Type:FlowMod]	
	3.504354	Controller	Node_9	OF-M-Ext	1315 > 58132 [Type:FlowMod]	
Provision	3.504363	Controller	Node_7	OF-M-Ext	1315 > 35309 [Type:Barrier_Request	t]
	3.504616	Controller	Node_10	OF-M-Ext	1315 > 41148 [Type:Barrier_Request	t]
a multicast -	3.504630	Controller	Node_9	OF-M-Ext	1315 > 58132 [Type:Barrier_Request	t]
session	3.504632	Node_7	Controller	OF-M-Ext	35309 > 1315 [Type:Barrier_Reply]	
	3.505130	Node_10	Controller	OF-M-Ext	41148 > 1315 [Type:Barrier_Reply]	
	3.505136	Node_9	Controller	OF-M-Ext	58132 > 1315 [Type:Barrier_Reply]	
	3.507416	Controller	Node_9	OF-M-Ext	1315 > 58132 [Type:Packet_Out]	

Figure 11: Wireshark capture for the OF messages involved in provisioning a session.

```
⊽ Header
   version: 1
   Type: FlowMod (14)
   length: 112
   xid: 75
                    Multicast group
⊽ Match
   Inport: 65534
                        address
   Match_Type
 Multicast_Group_Address: 7
   Starting_Frequency: 0
   Number_of_Frequency_Slots: 0
   Re_Flag: Dynamic_Multicast_Service (0)
   Command: Set_Up_New_Connection (0)
   IdleTimeout: 2
   HardTimeout: 0
   Priority: 32768
   BufferId: 4294967295
   OutPort: Any (65535)
   Flags: 0
✓ Actions
   action_type: SET_STARTING_FS (13)
   Starting_FS: 0
   action_type: SET_NUMBER_OF_FS (14)
   Number_of_FS: 1
   action_type: OUTPUT (0)
   Output_Port: 1
```

Figure 12: Flow\_Mod messages received on the source for setting up a logic multicast-tree.



Figure 13: *Flow\_Mod* messages received on a destination with a downstream member for setting up a logic multicast-tree.



Figure 14: *Flow\_Mod* messages received on a destination without a downstream member for setting up a logic multicast-tree.

Time	Source	Destination	Protocol	Info	
5.649607	Controller	Node_7	OF-M-Ext	1315 > 35309 [Type:FlowMod]	
5.649787	Controller	Node_8	OF-M-Ext	1315 > 39563 [Type:FlowMod]	Set up
5.687413	Controller	Node_8	OF-M-Ext	1315 > 39563 [Type:Barrier_Request]	new path
5.688092	Node_8	Controller	OF-M-Ext	39563 > 1315 [Type:Barrier_Reply]	new pau
5.689146	Controller	Node_7	OF-M-Ext	1315 > 35309 [Type:Barrier_Request]	
5.689799	Node 7	Controller	OF-M-Ext	35309 > 1315 [Type:Barrier_Reply]	Tear dow
5.690151	Controller	Node_10	OF-M-Ext	1315 > 41148 [Type:FlowMod]	old path
5.690328	Controller	Node_7	OF-M-Ext	1315 > 35309 [Type:FlowMod]	

Figure 15: Wireshark Capture for the OF messages involved in reconfiguration a session.

on DC 10 has 2 forwarding actions, and needs to output the flow to both the local port and DC 7.

We then consider the case that tree rearrangement is invoked, and conduct 392 an online reconfiguration experiments. Here, we assume that due to the dy-303 namic join-ins of multicast group members, the multicast-tree mentioned above 394 becomes  $\{9 \rightarrow 10, 10 \rightarrow 7, 7 \rightarrow 5, 9 \rightarrow 8\}$ , on which *DCs* 7 and 10 have al-395 ready left the session and become NM-RNs. Apparently, the multicast-tree is 396 sub-optimal and we can calculate the optimal one as  $\{9 \rightarrow 8, 8 \rightarrow 7 \rightarrow 5\}$ . 397 Here, we implement a full rearrangement and the Wireshark capture for the 398 OF messages used to reconfigure the multicast session is illustrated in Fig. 15. 399 Basically, we need to set up new connection of  $8 \rightarrow 7 \rightarrow 5$  and tear down the 400 original ones of  $\{9 \rightarrow 10, 10 \rightarrow 7\}$ . The details on the *Flow\_Mod* messages 401 used in the multicast-tree rearrangement are shown in Fig. 16. Here, we can 402 see that the *Flow\_Mod* message received on the OF-AG on *DC* 8 includes a 403 SET\_MULTICAST\_GROUP\_ADDRESS action to change the multicast 404 group address of the session, as the multicast group has been changed. 405

Finally, we perform dynamic networking experiments to test the system's performance under the situation that the multicast sessions can come, change and leave on-the-fly. Here, we test two algorithms, *i.e.*, N/R and QTS-P-0.7, and Fig. 17 shows the experimental results on blocking probability. For each traffic load, we test around 20000 dynamic requests from the OF-AGs in the testbed, and we invoke a rearrangement every time when 100 requests have expired in the SD-EON. As expected, QTS-P-0.7 provides significantly better blocking



(b) Tear down old connections of  $\{9 \rightarrow 10, 10 \rightarrow 7\}$ .

Figure 16: *Flow\_Mod* messages used to rearrange a multicast session.



Figure 17: Experimental results on blocking probability.



Figure 18: Experimental results on latency per rearrangement operation.

<sup>413</sup> performance than N/R, which verifies that the control plane system operates
<sup>414</sup> correctly to facilitate dynamic formulation of multicast sessions in an inter-DC
<sup>415</sup> SD-EON. Fig. 18 shows the average latency per reconfiguration operations of
<sup>416</sup> QTS-P-0.7. When the traffic load is 600 Erlangs, the latency is 263 milliseconds.
<sup>417</sup> The number of lightpaths rearrangement increases with the traffic load, thus the
<sup>418</sup> latency also increases.

#### 419 7. Conclusion

In this paper, we considered the dynamic formulation of multicast sessions 420 in inter-DC EONs built with MI-BV-WSS'. As the changing of multicast group 421 members can degrade the optimality of multicast-trees, we proposed selective 422 multicast rearrangement schemes for efficient service provisioning. Specifically, 423 we tried to rearrange the multicast-trees adaptively to reduce their spectrum 424 usages. Meanwhile, we aimed at minimizing the frequency of rearrangements to 425 avoid unnecessary operation complexity. Based on these considerations, we de-426 signed several multicast-tree rearrangement algorithms for updating multicast 427 sessions dynamically with lightpath reroutings. Both partial and full multicast-428 tree rearrangements were considered. Simulation results indicated that the pro-429 posed algorithms could rearrange the multicast-trees intelligently such that the 430 blocking probability could be reduced effectively with the least number of light-431 path reroutings. Among all the proposed algorithms, the QTS-based algorithm 432 achieved the best tradeoff between the blocking performance and the operation 433 complexity due to lightpath reroutings. Based on the theoretical investigations, 434 we investigated how to implement the proposed algorithms in the control plane 435 of an inter-DC SD-EON. We extended the OF protocol to support the dynamic 436 formulation of multicast sessions and also designed the functional models in the 437 control plane elements to realize multicast-tree rearrangements. Experiment 438 results verified the effectiveness of our proposed algorithms and system design. 439

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